

22/05/2025 TE MECHANICAL SEM-VI C-SCHEME AAI QP CODE:10083577

Time: 3 Hours

Total Marks: 80

Note: 1) Question No.1 is **Compulsory**

2) Attempt any three questions out of the remaining five questions.

3) Figures to the right indicate full marks.

4) Assume suitable data wherever required.

Q1 Attempt any four

(20)

- A. Explain the impact of automation on productivity and cost in manufacturing systems.
- B. What is the difference between uninformed and informed search algorithms? Explain with examples.
- C. What are the basic components of an Artificial Neural Network? List and explain briefly.
- D. Define a point-to-point control system used in the robotic system with suitable applications.
- E. What is latching in PLC programming? Draw a ladder diagram to demonstrate latching using a push button.

Q2 A Design simple pneumatic circuit for two-cylinder operation with the following sequence using 4/2 pilot-operated valve as DCV using cascade method
Delay B+ A+ A- B-, With user option of single cycle – multi cycle. Also draw displacement diagram. **(10)**

B Compare supervised learning with unsupervised learning. Discuss their major differences in data labelling, model training, and algorithm use. **(10)**

Q3 A What is meant by agent and explain its types with reference to Artificial Intelligence. (include sketches) **(10)**

B Illustrate with neat sketches mechanical and magnetic type of end effectors used in robotic system, stating its advantages and disadvantages. **(10)**

Q4 A Compare BFS and DFS based on the following parameters: **(10)**

- i) Approach (Strategy), ii) Data structure used, iii) Time complexity, iv) Space complexity, v) Completeness and optimality

B Illustrate with neat sketch hydraulic intensifier circuits. **(10)**

Q5 A Design electro-pneumatic circuit for two-cylinder operation with the following sequence using 5/2 both side solenoid-operated valve as DCV.
A+B+Delay B- A- , With user selection option single cycle Multicycle operation. **(10)**

B How do pitch, yaw, and roll relate to the degrees of freedom in a robot? Explain with examples. **(05)**

C Illustrate with neat sketches, the logic of AND and OR gates, used in operation of pneumatic circuits. **(05)**

Q6 A Define Natural Language Processing (NLP). Explain its role and applications in industrial automation. **(10)**

B Differentiate between PLC and Relays. **(05)**

C Illustrate K nearest neighbours algorithm used in machine learning. **(05)**