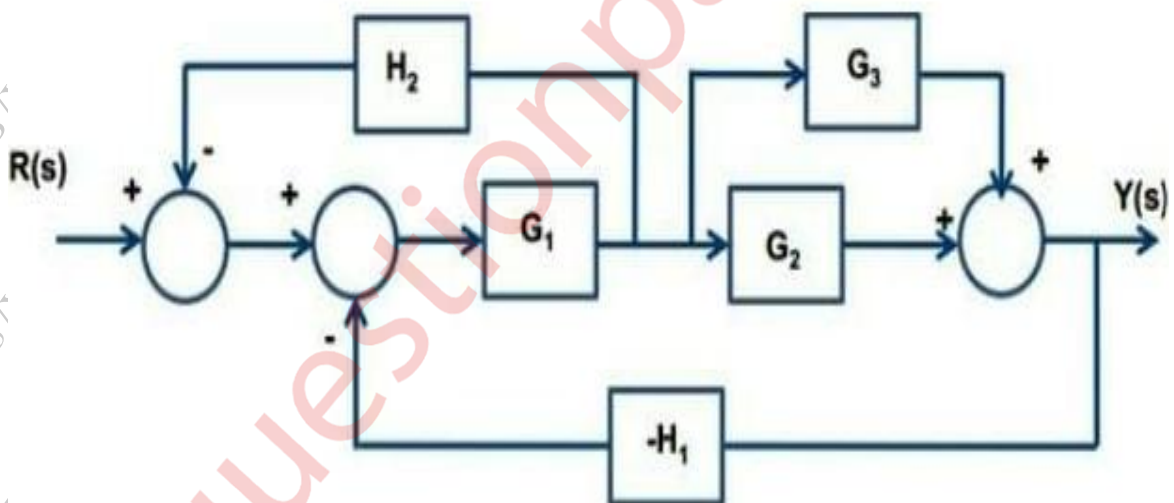


Duration 3 Hours

[Maximum Marks 80]

- NOTE:** 1) Question 1 is **compulsory**
 2) Solve **any three** from the remaining five questions
 3) Assume suitable data if necessary.
 4) Figures to the right indicate full marks

- Q.1.** a Explain any five rules of Root locus method. 5
 b. Define the following terms related to stability analysis using bode plot. 5
 (i) Gain Crossover Frequency
 (ii) Gain Crossover Frequency
 (iii) Gain Margin
 (iv) Phase Margin
 c. Compare open loop transfer function and closed loop transfer function with proper block diagram and Example. 5
 d. Explain Mason Gain's formula with its need. 5
- Q.2. a.** Find the overall transfer function of the given system using block diagram reduction method. 10



- b. The characteristic equation of a system is, determine range of K for stability. 10

$$S^4 + 7S^3 + 10S^2 + 2KS + K = 0.$$

Q3. a. A second order system is given by: **10**

$$\frac{C(S)}{R(S)} = \frac{25}{(S^2+6s+25)}$$

Find damping ratio, natural frequency, delay time, peak time, peak-overshoot, settling time if subjected to step input.

b. Draw polar plot of $G(s) H(s) = \frac{K}{(1+2S)(1+3S)}$ **10**

Q.4.a. Sketch the Root locus for given open loop transfer function and comment on the stability. **10**

$$G(s) H(s) = \frac{K}{s(s+5)(s+10)}$$

b. Check the controllability and observability of the following state model **10**

$$\dot{x} = Ax + Bu$$

$$Y = Cx$$

where x is the state vector, u is input and y is output and

$$A = \begin{bmatrix} -2 & 4 \\ 2 & 1 \end{bmatrix} \quad B = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \quad \text{and} \quad C = [1 \quad 0]$$

Q.5. a. Draw the Nyquist plot for the given open loop transfer function and test the stability. **10**

$$G(s) H(s) = \frac{1}{S^2(1+s)(1+2s)}$$

b. Obtain the state model for the system with given transfer function. **10**

$$\frac{Y(s)}{U(s)} = \frac{24}{s^3+9s^2+26s+24}$$

Q.6. Short note on (Any 2) **20**

a. Pole Placement method

b. Lag-lead compensator

c. Explain the Time domain specifications for second order under damped system.
