Paper / Subject Code: 89304 / Signals and Systems

May 27, 2024 02:30 pm - 05:30 pm 1T00836 - T.E.(Electrical Engineering)(SEM-VI)(Choice Base Credit Grading System) (R- 19) (C Scheme) / 89304 - Signals and Systems QP CODE: 10056446

Time (3 Hours) Marks: 80

Note: (1) Question no. 1 compulsory

- (2) Attempt any 3 question out of remaining five questions.
- (3) Draw neat diagram wherever necessary.

Q 1. Attempt any Four out of Six questions (5 marks each)

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- a. Check whether the given system y(n) = |x(n)| is linear/non-linear, time variant/time invariant static/dynamic, stable/unstable, causal/non causal systems.
- b. Explain Sampling theorem in detail.
- c. Discuss Rectangular, Hamming windows used to design FIR filters.
- d. Find the 4-point DFT of the sequence $x(n) = \{1, -2, 3, 2\}$.
- e. Explain ROC and its properties.
- f. Explain minimum phase, maximum phase and mixed phase systems with examples.
- Q 2. a. Obtain the Z-transform of

(10

- (1) x(n) = n(n+1) u(n)
- (2) x(n) = u(-n).
- b. Determine the periodicity of the following

(10)

- (1) $x(t) = 2 \cos 3t + 3 \sin 7t$
- (2) $x(t) = 5 \cos 4\pi t + 3 \sin 8\pi t$
- Q3. a. A LTI is described by the equation 2y(n) + 3y(n-1) + y(n-2) = u(n) + u(n-1) u(n-2). Find response of the system when the initial conditions are given by y(-1) = 2 and y(-2) = -1 and when unit step is applied as the input. (10)
 - b. Design a digital low pass FIR filter for a following specification

(10)

$$H_{d}(\omega) = \begin{cases} e^{-j\omega\tau} & \text{for } \omega \leq \omega_{C} \\ 0 & \text{otherwise} \end{cases}$$

Using rectangular window of length =7 & Wc=1rad/sample.

Q4. a. Determine inverse Z-transform of
$$X(z) = \frac{1}{1 - 1.5 z^{-1} + 0.5 z^{-2}}$$
 for ROC (1) $|z| > 1$ (2) $|z| < 0.5$ (3) $0.5 < |z| < 1$

b. Discuss the method of Bilinear transformation for design of IIR filter. (10)

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Q5. a. Explain any five properties of DFT

(10)

b. Compute DFT for the sequence $x(n) = \{0.5, 0.5, 0.5, 0.5, 0.5, 0.0, 0.0, 0.0\}$ using radix -2 DIT-FFT algorithm

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Q6. a) An LTI system is described by the equation:

(10)

Y(n) = x(n) + 0.8 x(n-1) + 0.8 x(n-2) - 0.49 y(n-2)

Determine the transfer function of the system, sketch poles and zeroes on the z-plane.

b) Find y(n) by using convolution if x(n) = [1,3,5,3] and h(n) = [2,3,1,1]

(10)

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