Paper / Subject Code: 89304 / Signals and Systems

12/12/2024 ELECTRICAL SEM-VI C SCHEME SIGNALS AND SYSTEMS QP CODE: 10056445

Duration: (3 Hours) Total Marks: 80

N.B: (1) Question No. 1 is compulsory.(any four)

- (2) Attempt any three from the remaining questions.
- (3) Assume suitable data wherever required.

Q1. a) Find out even and odd part of signal
$$x(t) = x(t) = (4 + sint)^2$$
. (20)

- b) Find the Z-transform of a signal given by $X(z) = \frac{1}{4} \frac{z^{-1}(1-z^{-4})}{(1-z^{-1})^2}$
- c) Find the N-point DFT of the following sequence

$$x = 5 + \cos^2\left(\frac{2\pi n}{N}\right)$$
 for n= 0,1.

d) Find the fundamental frequency in rad/s for a periodic signal

$$v(t) = 15\sin 100t + 05\cos 300t + 03\sin (500 + \frac{\pi}{4})$$

- e) Find the causal signal with Z- transform $z^2(z-a)^2$
- f) Consider a continuous -time system with i/p x(t) and o/p y(t) given by y(t) = x(t)cos(t) and explain in brief the given system is linear and time variant.

$$y(n)$$
- 3/4 $y(n-1)$ +1/8 $y(n-2) = 2x(n)$. Find $H(z)$.

b) Explain the disadvantages of direct computation of DFT and advantage of FFT. (10)

Find the 8-point DFT of the sequence $x(n) = \{1, 2, 3, 4, 4, 3, 2, 1\}$ using DIT-FFT radix-2 algo-

rithm.

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Q3 a) Find the 8-point DFT of the sequence $x(n) = \{1,2,3,4,4,3,2,1\}$ using DIT-FFT radix-2 algorithm. (10)

rithm.

- b) List the properties of region of convergence for the z-transform. (10)
- Q4). a) Explain any five properties of Z-transform. (10)
 - b. Using Bilinear transformation, obtain Butterworth filter design which satisfies the following conditions

$$0.8 \le |H(e^{jw})| \le 1$$
 $0 \le w \le 0.2 \pi$ (10)
 $|H(e^{jw})| \le 0.2$ $0.6 \pi \le w \le \pi$

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- **Q5**) a) Define LTI system. Check the causality, time invariance and linearity of the system $y(n) = x(n^2)$. (10)
 - b) State and prove the linearity and time reversal properties of Z- transform (10)
- Q6) (A) An LTI system is described by the equation: (10)

Y(n) = x(n) + 0.8 x(n-1) + 0.8 x(n-2) - 0.49 y(n-2).

Determine the transfer function of the system, sketch poles and zeroes on the z-plane.

(B) Find y(n) by using convolution if x(n) = [1,3,5,3] and h(n) = [2,3,1,1]. (10)

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