Paper / Subject Code: 36904 / CONTROL SYSTEM -I

Tuesday, May 28, 2019 02:30 pm - 05:30 pm 1T00816 - T.E.(ELECTRICAL)(Sem VI) (CBSGS) / 36904 - CONTROL SYSTEM -I 68764

(3 Hours) Total Marks: 80

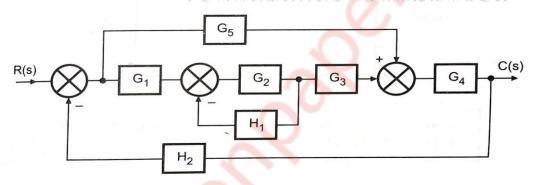
- N.B: (1) Question No.1 is compulsory.
 - (2) Attempt any **Three** from the remaining questions.
 - (3) Use graph paper and semi log paper wherever necessary.
- Q.1 Attempt any Four

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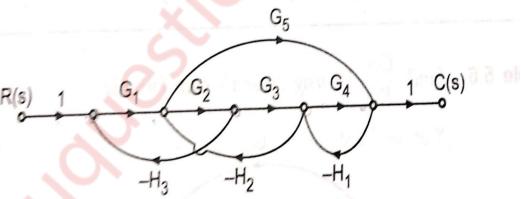
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- (a) Derive the expression to obtain transfer function from state model.
- (b) Define 'Stability', 'Unstability', Marginal Stability' with respect to pole position.
- (c) How to convert a system represented in state space to transfer function.
- (d) Explain Nyquist criteria for stability.
- (e) Explain the difference between open loop and closed loop systems.
- Q.2 (a) Reduce the block diagram to a single block $T(S) = \frac{C(S)}{R(S)}$



(b) Masson's gain formula to obtain the transfer function for the given figure

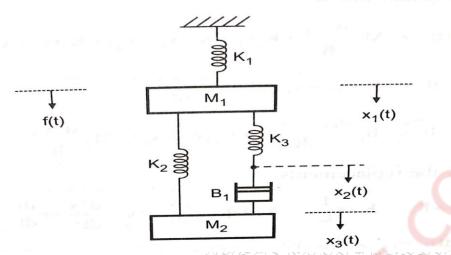


Q.3 (a) Find Kp, Kv, Ka and steady state error for a system with open loop transfer function as $G(S)H(S) = \frac{10(S+2)(S+3)}{S(S+1)(S+5)(S+4)}$. Where input is, $r(t)=3+t+t^2$.

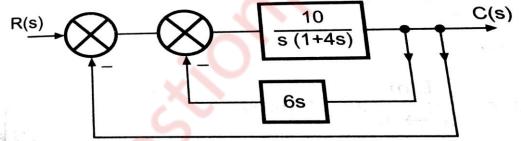
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(b) Draw the equivalent mechanical system of the given system. Hence write the set of equilibrium equation for it and obtain the force voltage analogy.



- Q.4 (a) Given the unity feedback system that has the transfer function $G(S) = \frac{K}{S(S+2)(S+4)(S+8)}$ Sketch the complete root locus.
 - (b) Using the routh table tell how many poles of the following equation are in the RHS, LHS & on the imaginary axis and also comment for stability $S^8+5S^6+2S^4+3S^2+1=0$
- Q.5 (a) For a given system find error coefficients and type of the system.



- (b) Draw the bode log magnitude & phase angle plots for the system given by $G(S)H(S) = \frac{80}{S(S+2)(S+20)}$ Find phase margin, gain margin, phase & gain crossover frequency. Also Comment on stability.
- Q.6 (a) Sketch the Nyquist plot for a system with $G(S)H(S) = \frac{10(S+3)}{S(S-1)}$
 - (b) Explain gain cross over frequency, phase cross over, gain margin and phase margin in frequency response technique.