

(3 Hours)

Total Marks: 80

N.B.: 1. Question No.1.iscompulsory.

2. Attempt any **three** questions out of the remaining **five** questions.3. Assume **suitable** data wherever **required**.4. **Figures** to the **right** indicates **full** marks.

- Q1. a. Derive the transfer function of mercury in glass thermometer [5]
 b. Compare PI and PID control system. [5]
 c. Differentiate between servo problem and regulatory problem. [5]
 d. Describe Bode stability criterion. [5]
- Q2. a. Derive the step response of a first order system [6]
 b. A thermometer having first order dynamics with a time constant of 1 min is placed in a temperature bath at 100 °C. After the thermometer reaches steady state, it is suddenly placed in a bath at 110 °C at t=0 and left there for 1 min, after which it is immediately returned to the bath at 100 °C. Calculate the thermometer reading at t=0.5 min and at t=2.0 min. [8]
 c. Compare step response and impulse response of a first order system. [6]
- Q3 a. Draw the root locus for the system having open loop transfer function as
- $$G(s)H(s) = \frac{K}{s(s+4)(s+2)} \quad [15]$$
- b. Compare interacting and non-interacting system [5]
- Q4. a. For a unity feedback system $G(s) = \frac{80}{s(s+2)(s+20)}$ sketch the bode plot and comment on stability [15]
 b. Draw block diagram of a simple feedback control system with specification of each block [5]

Q5. a. Write the working principle and application of radiation pyrometer with neat diagram. [10]

b. Derive the transfer function of a two tank interacting system [10]

Q6 Write short notes on (any **four**) [20]

a. Role of damping coefficient in second order system

b. Cascade control system

c. Routh test for stability analysis

d. Final control element

e. Nyquist stability criteria
