

13-05-16

Q.P. Code : 551102



(3 Hours)

[Total Marks : 80

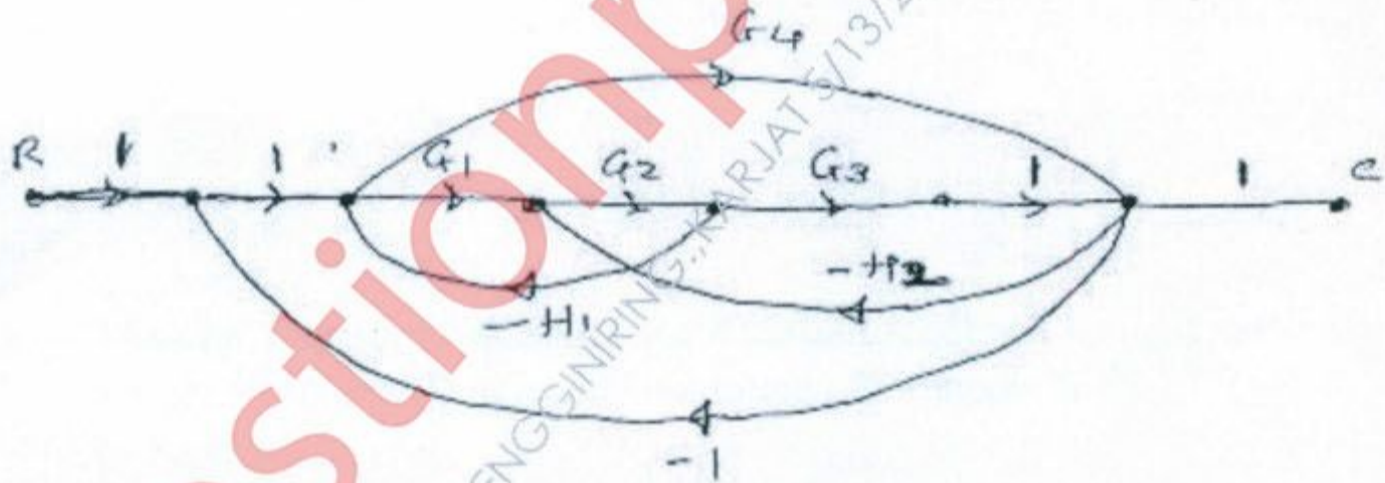
- N.B. :**
- (1) Question No. 1 is **compulsory**
 - (2) Attempt any **three** questions out of **remaining five** questions
 - (3) Assume Suitable data, if necessary
 - (4) Figure to the right indicated full marks

1. Attempt any **four**

20

- (a) Compare openloop and closed loop system
- (b) Explain Regenrative feedback
- (c) Explain the principle of superposition
- (d) Explain co-rrelation between time and frequency response
- (e) What is the errect of adding zeros to the system

2. (a) Obtain the overall transfer function C/R from the signal flow graph 10 shown in figure.



(b) A unity feedback control system has a open loop transfer function 10

$$G(s) = \frac{k}{s(s^2 + 4s + 13)}$$

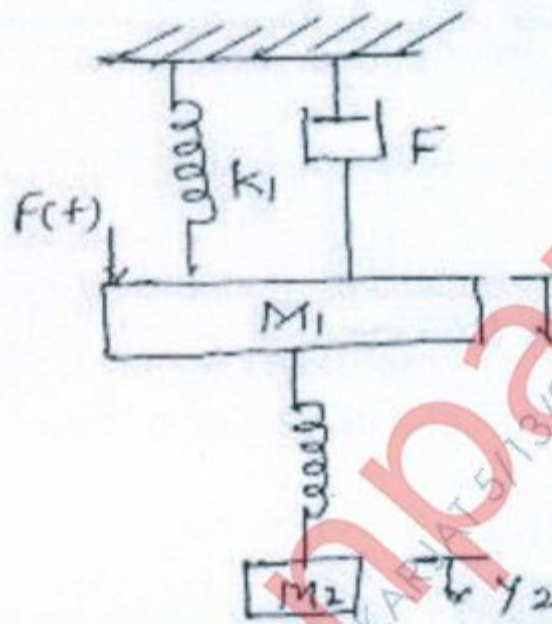
sketch the rootlocus plot of a system. Find the value of K and frequency at which the root loci cross the jw axis.

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3. (a) Sketch the bode plot and determine the gain cross over frequency for the transfer function given below. 10

$$G(s) = \frac{4}{s(1+0.5s)(1+0.08s)}$$

- (b) Write the differential equations governing the behaviour of mechanical system shown in figure. Also obtain an analogous electrical circuit based on Force-Voltage analogy. 10



4. (a) The characteristic equations for a certain feedback control systems are given below. Determine the range of values of K for the system to be stable. 10

(i) $s^4 + 22s^3 + 10s^2 + 2s + k = 0$

(ii) $s^4 + 12s^3 + 69s^2 + 198s + (20+k) = 0$

- (b) The closed loop transfer function of the second order system is 10

$$\frac{C(s)}{R(s)} = \frac{\omega_n^2}{s^2 + 2\zeta\omega_n s + \omega_n^2}$$

obtain the equation for the output response

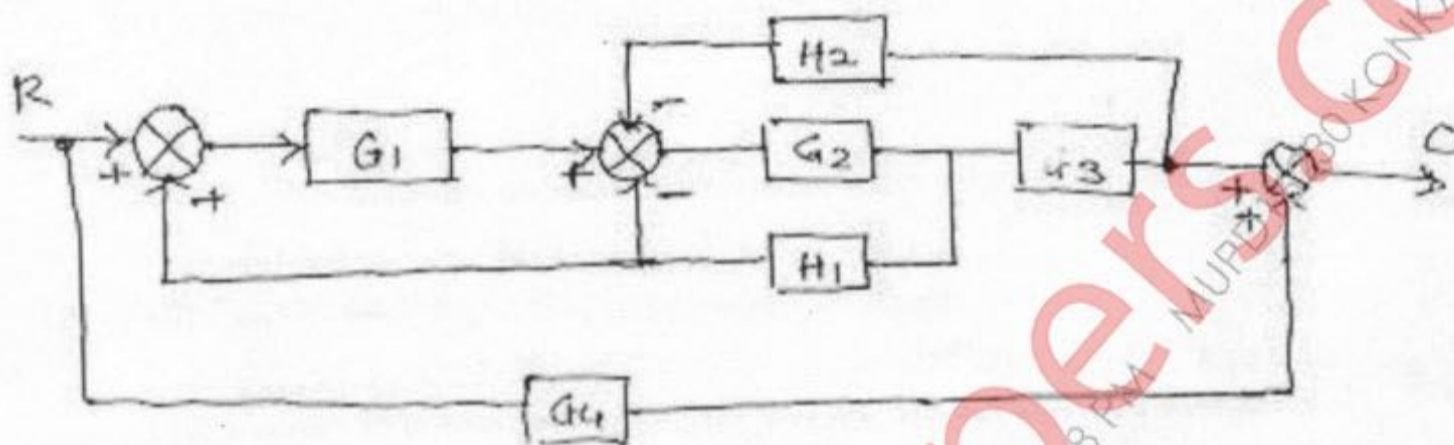
c(t) for unit step input for under damped

5. (a) (i) Sketch the polar plot of the transfer function given below 10

$$G(s) = \frac{1}{(1+s)(1+2s)}$$

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- (ii) Define the gain margin and phase margin
 (b) Using the block diagram reduction techniques, find the closed loop transfer function of the system given below. 10



6. (a) (i) Explain the dominant condition 5
 (ii) Explain Nyquist stability criterion. 5

- (b) A unity feedback system has a transfer function $G(s) = \frac{25}{s(s+8)}$ 10

Determine damping ratio, peak overshoot Rise time and settling time.