S.E. SEM - IV / CBSGS / INST / ELECTRICAL TECHNOLOGY & INSTRUMENTATION / 05.12.17

Q.P. Code: 25397

Total Marks: 80 **Duration: 3 Hours** Note: 1) Question no 1 is compulsory 2) Solve any three questions from remaining questions 3) Assume suitable data if required and mentioned it 20 0.1 Solve a) Explain the types of DC motor b) Explain the use of slip rings and brush assembly. c) State the advantages of using the bridge circuits for the measurement. d) What is sensitivity of voltmeters? Explain. a) A 230V, d.c. Shunt motor takes a no load current of 3A and runs at 1100 r.p.m. 10 Q.2 If the full load current is 41A, find the speed on Full load. Assume armature resistance as 0.25Ω and that of shunt field winding as 230Ω . b) Explain the Torque slip characteristics of 3 phase induction motor. 10 10 Q.3 a) Explain constructional details of PMMC instruments b) A bridge is shown in the figure. Calculate the current through Galvanometer. 10 where Rg = 300Ω $2K\Omega$ $4K\Omega$ 20KΩ -8V Q. 4) a) Explain how rotating magnetic field is produced in 3 phase induction motor 10 b) Explain Kelvin's double bridge for low value resistance measurement? Derive the 10 expression Q. 5) a) A 3phase, 4 pole, 50Hz induction motor has a star connected rotor. The voltage 10 across each phase of the rotor at standstill is 121 V. The rotor resistance is 0.3Ω and standstill reactance is 0.8Ω per phase. If in the running condition rotor current per phase is 15A, calculate the speed at which it is running. 10 b) Explain losses in three phase induction motor Q.6) Write short notes on (any two) 20 1) Star Delta Starter

2) Megger

3) Analog to Digital Gopperter 635C0F46D54074DED018230