

N.B:

- 1) Question 1 is compulsory. Answer any three questions from the remaining.
- 2) Assume data if necessary and specify the assumptions clearly
- 3) Draw neat sketches wherever required
- 4) Answer to the sub-questions of an individual question should be grouped and written together.

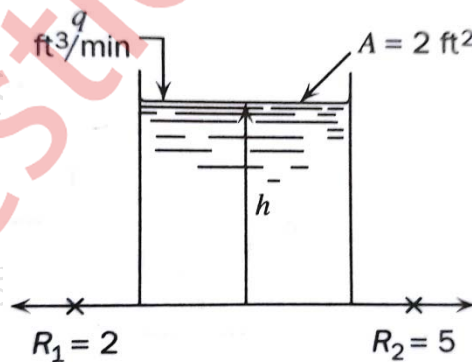
Q.1.a) Discuss degrees of freedom analysis for process (N_F) and degrees of freedom analysis for process control (N_{FC})? Also discuss the relation between them [05]

Q.1.b) Explain Phase Margin and Gain Margin? [05]

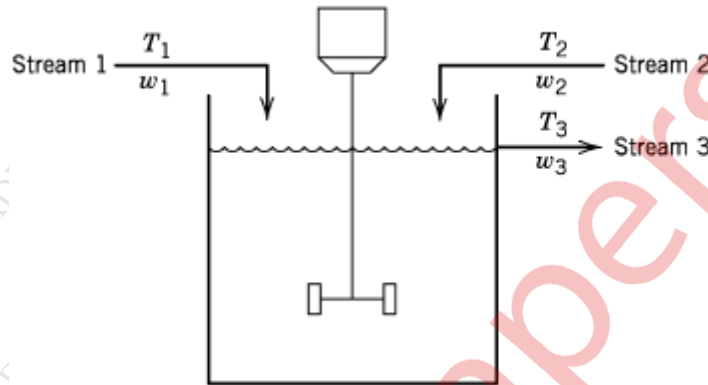
Q.1.c) Define a unit pulse function mathematically and graphically. Also derive the Laplace transform [05]

Q.1.d) Discuss performance criteria for closed loop systems [05]

Q.2.a) Derive the transfer function H/Q for the liquid level system shown in figure. The resistances are linear. H and Q are deviation variables. Show clearly how you derive the transfer function. You are expected to give numerical values in the transfer function [10]



- Q.2.b) A perfectly stirred, constant-volume tank has two input streams, both consisting of the same liquid. The temperature and flow rate of each of the streams can vary with time. Derive a dynamic model that will describe transient operation. Also perform degrees of freedom analysis assuming that both Streams 1 and 2 come from upstream units (i.e., their flow rates and temperatures are known functions of time). *Notes: w_i denotes mass flow rate for stream i . Liquid properties are constant (not functions of temperature).* [10]



- Q.3.a) consider the following transfer function

$$G(s) = \frac{Y(s)}{U(s)} = \frac{3}{10s + 1}$$

Find the steady state gain and time constant?

If $U(s) = 2/s$, what is the value of the output $y(t)$ when $t \rightarrow \infty$?

For the same $U(s)$, what is the value of the output when $t=10$?

If $U(s) = (1-e^{-s})/s$, that is the unit rectangular pulse, what is the output when $t \rightarrow \infty$?

If $u(t) = \delta(t)$, that is the unit impulse at $t=0$, what is the output when $t \rightarrow \infty$? [10]

- Q.3.b) The dynamic behavior of the liquid level in each leg of a manometer tube, responding to a change in pressure, is given by where $h(t)$ is the level of fluid measured with respect to the initial steady-state value, $p(t)$ is the pressure change, and R, L, g, ρ , and μ are constants. [10]

$$\frac{d^2 h}{dt^2} + \frac{6\mu}{R^2 \rho} \frac{dh}{dt} + \frac{3g}{2L} h = \frac{3}{4\rho L} p(t)$$

- (i) Rearrange this equation into standard gain-time constant form and find expressions for K , τ and ξ in terms of the physical constants.
- (ii) For what values of the physical constants does the manometer response oscillate?
- (iii) Would changing the manometer fluid so that ρ (density) is larger make its response more oscillatory, or less?

Q.4.a) Explain in detail Turbine Flow meter with neat diagram [10]

Q.4.b) Consider a feedback control system with process transfer function of $5/(10s+1)$, disturbance transfer function of $-0.5/(10s+1)$, measurement dynamics $1/(0.1s+1)$ and valve dynamics of $1/(s+1)$. This process is controlled by a P controller with gain 0.45. What will be the offset if the set point is changed by 2 units? [10]

Q.5.a) For a system with $G(s)H(s) = \frac{K(1+s)^2}{s^3}$ find range of 'K' for system to be stable [10]

Q.5.b) For unity feedback system with $G(s) = \frac{10}{s(s+1)(s+5)}$ sketch the Bode plot. Find Gain margin, Phase margin, Gain cross over frequency, phase cross over frequency and Comment on stability [10]

Q.6.a) Define all performance characteristics of instruments in detail [10]

Q.6.b) Discuss continuous cycling controller tuning method in detail with steps [10]