

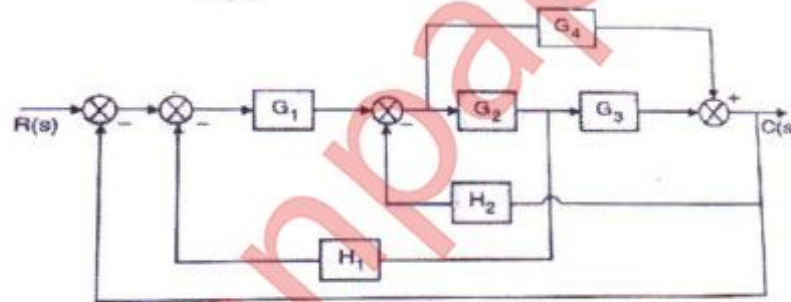
(3 hours)

Total

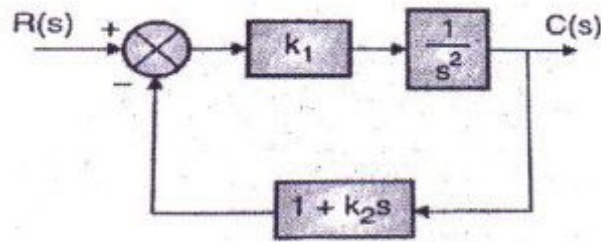
Marks: 80

- N.B.: (1) Question No. 1 is compulsory.
 (2) Solve any three questions from remaining five questions.
 (3) Draw neat diagrams and assume suitable data wherever necessary. Justify your assumptions.

1. Attempt any **four**: 20
- Compare open loop and closed loop control system.
 - Differentiate analog and digital control system.
 - State and explain rules for constructing a root locus.
 - Explain the terms i) Centroid ii) Angle of asymptotes ii) break away point.
 - Write a short note on digital control system.
2. (a) Find the transfer function $\frac{C(s)}{R(s)}$ using Block Diagram Reduction Technique: 10



- (b) Draw the Nyquist plot if the given system and comment on its stability. 10
- $$G(s) = \frac{1}{s(s+4)(s+8)}$$
3. (a) A feedback control system has open loop transfer function 12
- $$G(s)H(s) = \frac{k}{s(s+4)(s^2+4s+20)}$$
- Plot the root locus for $k=0$ to ∞ indicate all the points on it.
- (b) Explain the realization of lag-lead compensator using electrical network. 8
4. (a) For the control system shown below find k_1 and k_2 so that $M_p = 25\%$ and $t_p = 4$ 10
 sec. Also find i) Settling time ii) Rise time



- (b) Define i) Delay Time ii) Rise Time iii) Peak Time iv) Settling Time v) Peak overshoot 10
5. (a) For the transfer function given below $G(s)H(s) = \frac{48(s+10)}{s(s+20)(s^2+2.4s+1)}$ 10
 Find:
 i) Static position error coefficient
 ii) Static velocity error coefficient
 iii) Static acceleration error coefficient
 iv) Steady state error if the input to the system is unit step
- (b) For the unity feedback control system $G(s) = \frac{10}{s(s+1)(s+5)}$. Sketch the bode plot. 10
 Determine gain and phase margin.
6. (a) Explain implementation of digital controller in temperature control system. 10
 (b) Find the range of k so that the following system are stable using Routh's stability criteria: 10
 i) $s^4 + 7s^3 + 10s^2 + 2ks + k = 0$
 ii) $s^3 + 3ks^2 + (k+2)s + 4 = 0$