

23/05/2016 TE ELX (CBSCS) SEM-V SWB M & A.

QP Code : 31131

(3 Hours)

Total Marks: 80

- N.B. 1) Question number 1 is compulsory.
2) Attempt any three from remaining five questions.
3) Assume suitable data wherever necessary.
4) Figure to the right indicates full marks.

Q1. Attempt any four from the following.

(20)

- Explain the difference between RET and RETI instructions as implemented in 8051 architecture.
- What is the maximum address range of conditional jump instructions for 8051 architecture and justify the reason for the same.
- Illustrate the circuit representation for interfacing single LED and relay to the port pins of 8051 architecture based processor.
- Explain pipelining feature in ARM7TDMI architecture. Justify advantages and disadvantages.
- Explain the significance of letters and numbers in – 'ARM7TDMI'.
- Explain the bit orientations of CPSR register for ARM7TDMI architecture.

Q2a) Write a note on the various modes of operation of ARM7TDMI based processor.

(10)

b) Explain the following 8051 architecture based instructions:

a) MOV C,0X10 b) MUL AB c) MOVC A, A+@0x2000 d) INC 0x45

e) ANLA,@R0

(10)

Q3 a) With a neat circuit representation illustrate interfacing of a typical 8-bit DAC to 8051 architecture based processor. Using DAC write a program in 8051 assembly to generate a triangular wave.

(12)

b) Explain the programmer's model (register structure) in ARM7TDMI architecture.

(08)

Q4a) Explain the various addressing modes with suitable examples available in 8051-architecture.

(10)

b) Using internal timers write a program in 8051 assembly to generate a square wave of 10kHz frequency and 50% duty cycle on port pin P1.0.

(10)

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Q5)a) Explain the following ARM7TDMI architecture based instructions as well as their implications. (10)

a) BL Square b) ADD R0, R1, R2, LSL#3 c) MOVEQS R1,R0 d) LDR R8, [R3, #4]
e) STR R2, [R1, #0x100]

b) Write a brief note on the process of interrupts and their mechanism of acknowledgement in 8051 – architecture. (10)

Q6) Write brief notes on.

a) ARM7TDMI thumb mode of operation. (07)

b) Interfacing stepper/continuous motor to 8051 based microcontroller. (07)

c) Serial port and modes of operation in 8051 architecture. (06)

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