

SE EXTC Sem-4 10/06/2014
Signal and Systems.

QP Code : NP-19845

(3 Hours)

[Total Marks M.sc. : 80

- N.B. : (1) Question No. 1 is compulsory.
(2) Attempt any **three** from remaining **five** questions.
(3) Assume **suitable data** if **required** justify the **same**.

1. (a) Determine power and energy for the following signals. 20

(i) $x(t) = 3 \cos 5 \Omega_0 t.$

(ii) $x[n] = \left(\frac{1}{4}\right)^n u[n]$

(b) State and prove the following properties of fourier transform :

(i) Time shifting property (ii) Convolution property.

(c) Compare linear convolution and circular convolution.

(d) Define and Explain :

(i) Auto correlation

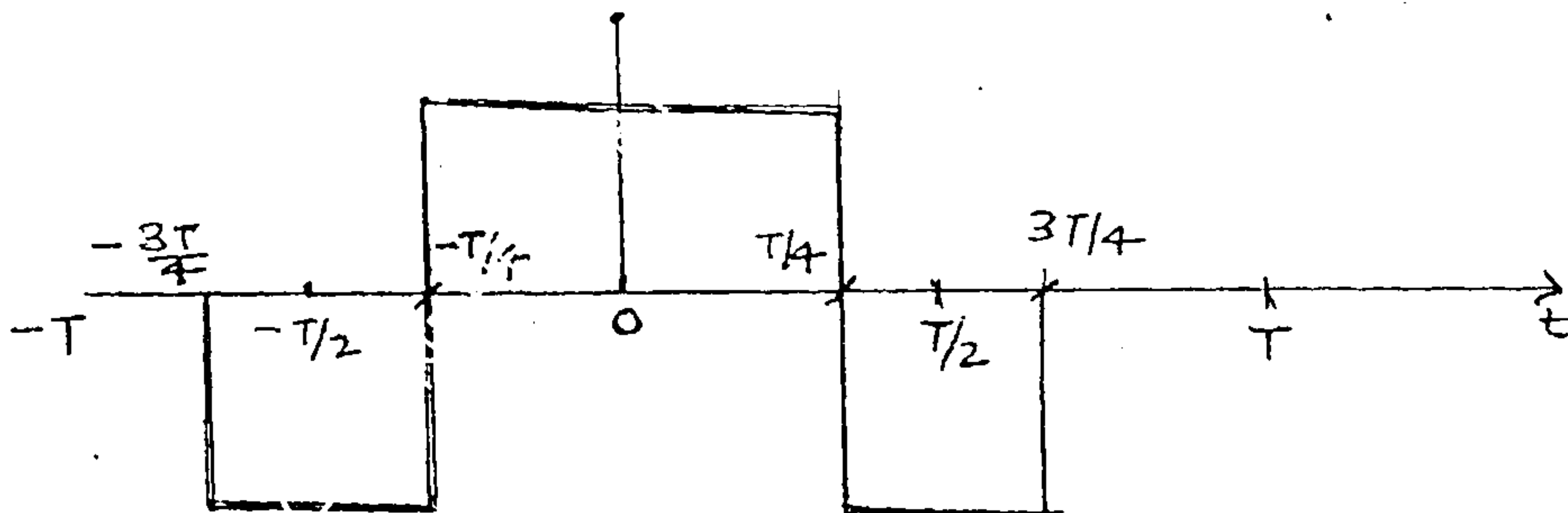
(ii) Cross correlation

(iii) Circular convolution.

(e) $x[n] = u[n] - u[n - 5].$

Sketch even and odd parts of $x[n].$

2. (a) Determine Fourier Series representation of the following signal :— 10



(b) For a continuous time signal $x(t) = 8 \cos 200 \pi t.$ 10

Find : (1) Minimum sampling rate.

(2) If $f_s = 400$ Hz, what is discrete time signal ?

(3) If $f_s = 150$ Hz, what is the discrete time signal ?

(4) Comment on result obtained in 2 and 3 with proper justification.

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3. (a) Determine the inverse z transform of the function using Residue method : 10

$$X(z) = \frac{3 - 2z^{-1} + z^{-2}}{1 - 3z^{-1} + 2z^{-2}}$$

- (b) Two LTI systems in cascade have impulse response $h_1[n]$ and $h_2[n]$ 10

$$h_1[n] = (0.9)^n u[n] - 0.5 (0.9)^{n-1} u[n-1]$$

$$h_2[n] = (0.5)^n u[n] - (0.5)^{n-1} u[n-1]$$

find the equivalent response $h[n]$ of the system.

4. (a) A causal LTI system is described $y[n] = \frac{3}{4} y[n-1] - \frac{1}{8} y[n-2] + x[n]$. 10

Where $y[n]$ response of the system and $x[n]$ is excitation to the system.

(i) Determine impulse response of the system.

(ii) Determine step response of the system.

(iii) Plot pole-zero pattern and state whether system is stable.

- (b) (i) Determine the z transform and the ROC of the discrete time signal. 5

$$x[n] = \{ 2, 10, 1, 2, 5, 7, 2 \}$$

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- (ii) Determine the inverse z-transform for the function : 5

$$X[z] = \frac{z^2 + z}{z^2 - 2z + 1} \quad \text{ROC } |z| > 1$$

5. (a) The impulse response of an LTI system $h[n] = \{1, 2, 1, -1\}$. Find the response $y[n]$ of the system for the input $x[n] = \{1, 2, 3, 1\}$ using Discrete time Fourier Transform. 10

- (b) Find the response of a system with transfer function $H(s) = \frac{1}{s+5}$ $\text{Re}(s) > -5$ 10

$$\text{Input } x(t) = e^{-t} u(t) + e^{-2t} u(t)$$

6. (a) For the given LTI system, described by the differential equation : 10

$$\frac{dy^2(t)}{dt^2} + \frac{3dy(t)}{dt} + 2y(t) = x(t)$$

Calculate output $y(t)$ if input $x(t) = e^{-3t} u(t)$ is applied to the system.

- (b) Find the autocorrelation, power and power spectral density of the signal 10

$$x(t) = 3 \cos t + 4 \cos 3t$$