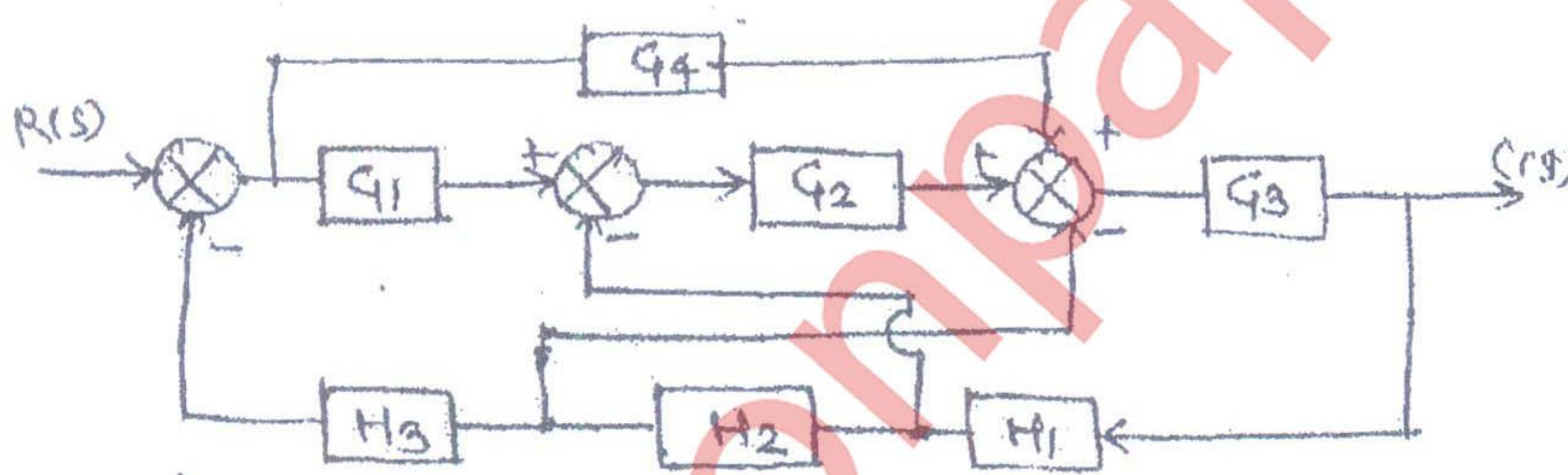


Please check whether you have got the right question paper.

- N.B:
1. Question No. 1 is compulsory.
 2. Attempt any three questions from remaining.
 3. Assume suitable data if required.
 4. Figure to the right indicate full marks.

1. Attempt any four from the following: 20
 - a) Explain any five rules of root locus plot.
 - b) What are the properties of state transition matrix.
 - c) Explain adaptive control system.
 - d) Describe the Mason's gain formula with an example.
 - e) Explain need of compensators.
2. a) Obtain the overall transfer function from block diagram. 10



- b) Find the solution of following state equation. 10

$$\dot{x} = \begin{bmatrix} -5 & -6 \\ 1 & 0 \end{bmatrix} x + \begin{bmatrix} 1 \\ 0 \end{bmatrix} u$$

$$y = [1 \quad 1] x$$

3. a) Explain the type of signal which produces a finite steady state error for following system. Also find the steady state error. 10

- i) $G(s)H(s) = \frac{20}{(S+2)(S+3)}$

- ii) $G(s)H(s) = \frac{20(S+1)}{S^2(S+2)(S+4)}$

- iii) $G(s)H(s) = \frac{2.5(S^2 + 2S + 1)}{S(S+1)(S^2 + 5S + 2)}$

- b) Derive an Expression for output response of a second order under damped control system. Assume the input to be unit step signal. 10

Turn Over

4. a) Draw the root locus for the system with $G(s)H(s) = \frac{K(S+2)(S+3)}{S(S+1)}$ and comment on stability. 10
- b) Determine the stability of the system having characteristic equation $S^5 + S^4 + 2S^3 + 3S + 5 = 0$ 10
5. a) Draw Bode plot and find gain margin and phase margin for $G(s)H(s) = \frac{64(S+2)}{S(S+0.5)(S^2+3.2S+64)}$ 10
- b) Discuss the stability of system using Nyquist plot for $G(s)H(s) = \frac{20}{S(S+4)(S-2)}$. 10
6. Attempt any two 20
- a) Different composite controllers.
- b) Co-relation between time domain and frequency domain specification.
- c) Using Mason's gain formula, find the gain of the following system in figure below.

