

Duration:-03 Hrs

Total marks assigned to the paper: - 80

**Instructions to the candidates if any:-**

1. Question No 1 is compulsory
2. Attempt any three questions from the remaining five questions
3. Assume suitable data wherever necessary
4. Figures to the right indicates full marks

**Q. No. 1**

- a. Write a short note on Adaptive control systems. [05]
- b. Write a short note on Smith Predictor [05]
- c. Write a short note on batch process optimization [05]
- d. Derive discrete transfer function for PI controller [05]

**Q. No. 2**

- a. Derive equation for moving average filter [10]
- b. A process has the following transfer function [10]

$$G(s) = \begin{bmatrix} \frac{-2e^{-s}}{s+1} & \frac{1.5e^{-s}}{s+1} \\ \frac{1.5e^{-s}}{s+1} & \frac{-2e^{-s}}{10s+1} \end{bmatrix}$$

Use the RGA approach to determine the recommended controller pairing based on steady state considerations

**Q. No 3**

- a. For the difference equation  

$$y(k) = 0.9744y(k-1) - 0.2231y(k-2) - 0.3225y(k-2) + 0.5712y(k-3)$$
 Derive its discrete transfer function [10]
- b. Discuss batch control systems [10]

**Q. No. 4**

- a. Discuss hypothetical plant for plant-wide control studies [10]
- b. Discuss the procedure for the design of plant wide control systems [10]

**Q. No 5**

- a. A signal is given by  $y_m(t) = t + 0.5\sin t(t^2)$  is to be filtered with an exponential digital filter over the interval  $0 \leq t \leq 20$ . Using two different values of  $\alpha$  (0.8 and 0.2) determine the output of the filter for a sampling period of 1 min. Plot the response for both the cases [10]
- b. A  $2 \times 2$  process has the following steady state gain matrix

$$K = \begin{bmatrix} 1 & 0 \\ 10 & 1 \end{bmatrix}$$

Calculate the Eigen values, singular values and the condition number [10]

**Q. No 6**

Write short notes on the following [20]

- a. Types of filters
- b. Minimum Variance Control
- c. Cascade control
- d. Issues in Plant wide control

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